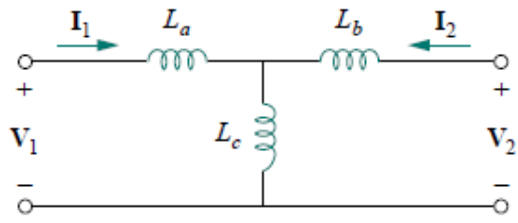
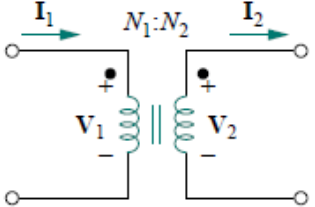


Formulário

$z = r \angle \phi = re^{j\phi}$	$z = x + jy = r \angle \phi = r(\cos \phi + j \sin \phi)$		
$i(t) = C \frac{du}{dt}$	$u(t) = L \frac{di}{dt}$	$V_{\text{rms}} = \frac{V_m}{\sqrt{2}}$	
$S = V_{\text{rms}} I_{\text{rms}}$		$P = V_{\text{rms}} I_{\text{rms}} \cos(\theta_v - \theta_i) = S \cos(\theta_v - \theta_i)$	$S = \frac{1}{2} \mathbf{VI}^*$
	$\text{pf} = \cos(\theta_v - \theta_i)$	$S = I_{\text{rms}}^2 (R + jX) = P + jQ$	
	$P = V_{\text{rms}} I_{\text{rms}} \cos(\theta_v - \theta_i),$	$Q = V_{\text{rms}} I_{\text{rms}} \sin(\theta_v - \theta_i)$	
$M = k\sqrt{L_1 L_2}$	$Z_{\text{in}} = \frac{V}{I_1} = R_1 + j\omega L_1 + \frac{\omega^2 M^2}{R_2 + j\omega L_2 + Z_L}$		
	 $\frac{V_2}{V_1} = \frac{N_2}{N_1} \quad \frac{I_2}{I_1} = \frac{N_1}{N_2}$	$L_a = L_1 - M \quad L_b = L_2 - M \quad L_c = M$	

$B = \frac{\phi}{a} \text{ Wb/m}^2$	$H = \frac{B}{\mu_0 \mu_r} = \frac{\phi}{a \mu_0 \mu_r} \text{ AT/m}$	$Hl = NI \quad \text{or} \quad \frac{\phi}{a \mu_0 \mu_r} \times l = NI \quad \text{c}$	$S = \frac{l}{a \mu_0 \mu_r}$																						
$e = N \frac{d\phi}{dt}$	$T = 2F_r \sin \theta$	$\omega T_e = \omega T_m - \omega T_f$	$ei = \omega T_e$																						
$E_g = \frac{PZ\phi N}{60A} \text{ volt.}$	$E I_a = \omega T_e$ $\frac{\phi ZNP}{60A} \times I_a = \frac{2\pi N}{60} \times T_e$	Terminal voltage, $V = E_g - I_a R_a$																							
	<table border="1"> <thead> <tr> <th>Element</th> <th>Time domain</th> <th>Frequency domain</th> </tr> </thead> <tbody> <tr> <td><math>R</math></td> <td><math>v = Ri</math></td> <td><math>\mathbf{V} = R\mathbf{I}</math></td> </tr> <tr> <td><math>L</math></td> <td><math>v = L \frac{di}{dt}</math></td> <td><math>\mathbf{V} = j\omega L\mathbf{I}</math></td> </tr> <tr> <td><math>C</math></td> <td><math>i = C \frac{dv}{dt}</math></td> <td><math>\mathbf{V} = \frac{\mathbf{I}}{j\omega C}</math></td> </tr> </tbody> </table>	Element	Time domain	Frequency domain	$R$	$v = Ri$	$\mathbf{V} = R\mathbf{I}$	$L$	$v = L \frac{di}{dt}$	$\mathbf{V} = j\omega L\mathbf{I}$	$C$	$i = C \frac{dv}{dt}$	$\mathbf{V} = \frac{\mathbf{I}}{j\omega C}$	<p><b>TABLE 9.1</b> Sinusoid-phasor transformation.</p> <table border="1"> <thead> <tr> <th>Time-domain representation</th> <th>Phasor-domain representation</th> </tr> </thead> <tbody> <tr> <td><math>V_m \cos(\omega t + \phi)</math></td> <td><math>V_m \angle \phi</math></td> </tr> <tr> <td><math>V_m \sin(\omega t + \phi)</math></td> <td><math>V_m \angle \phi - 90^\circ</math></td> </tr> <tr> <td><math>I_m \cos(\omega t + \theta)</math></td> <td><math>I_m \angle \theta</math></td> </tr> <tr> <td><math>I_m \sin(\omega t + \theta)</math></td> <td><math>I_m \angle \theta - 90^\circ</math></td> </tr> </tbody> </table>	Time-domain representation	Phasor-domain representation	$V_m \cos(\omega t + \phi)$	$V_m \angle \phi$	$V_m \sin(\omega t + \phi)$	$V_m \angle \phi - 90^\circ$	$I_m \cos(\omega t + \theta)$	$I_m \angle \theta$	$I_m \sin(\omega t + \theta)$	$I_m \angle \theta - 90^\circ$	
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